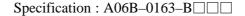
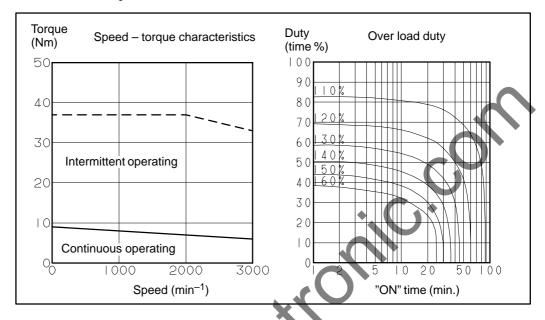
Model α M9/3000





Data sheet

Parameter		Symbol	Value	Unit
Rating rotation speed		Nmax	3000	min ⁻¹
Detect torque et etell	(*) Ts	9.0	Nm	
Rated torque at stall		IS	92	kgfcm
Rotor inertia	Jm	0.0025	kgm ²	
Rotormenta		JIII	0.026	kgfcms ²
Continuous RMS current	at stall (*)	Is	10.4	A (rms)
Towns	(*) Ki	1/4	0.86	Nm/A (rms)
Torque constant		Kī	8.8	kgfcm/A (rms)
Back EMF constant (1-ph	ase)			
	(*)	Ke	30	V (rms)/1000min ⁻¹
	(*)	Kv	0.29	V (rms)-sec/rad
Armature resistance (1–p	hase) (*)	Ra	0.181	Ω
Mechanical time constant	(*)	tm	0.002	s
Thermal time constant		tt	50	min
Static friction	Tf	Τ4	0.3	Nm
			3	kgfcm
Mass			12	kg

The speed-torque characteristics very depending on the type of software, parameter setting, and input voltage of the digital servo motor. (The above figures show average values.) These values may be changed without prior notice.

Fig. 3.3 (e) Models and α M6/3000 and α M9/3000 (standard)

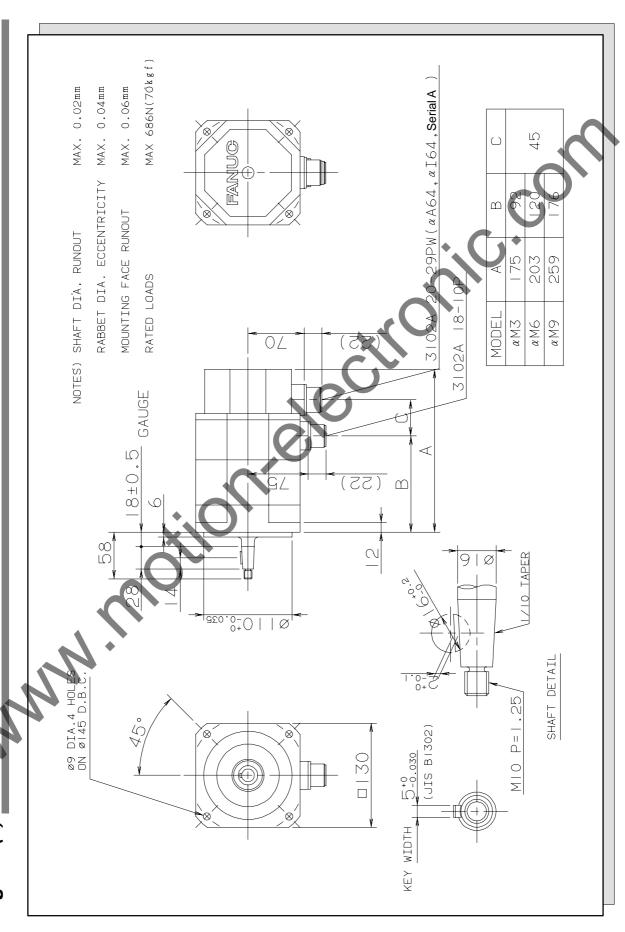
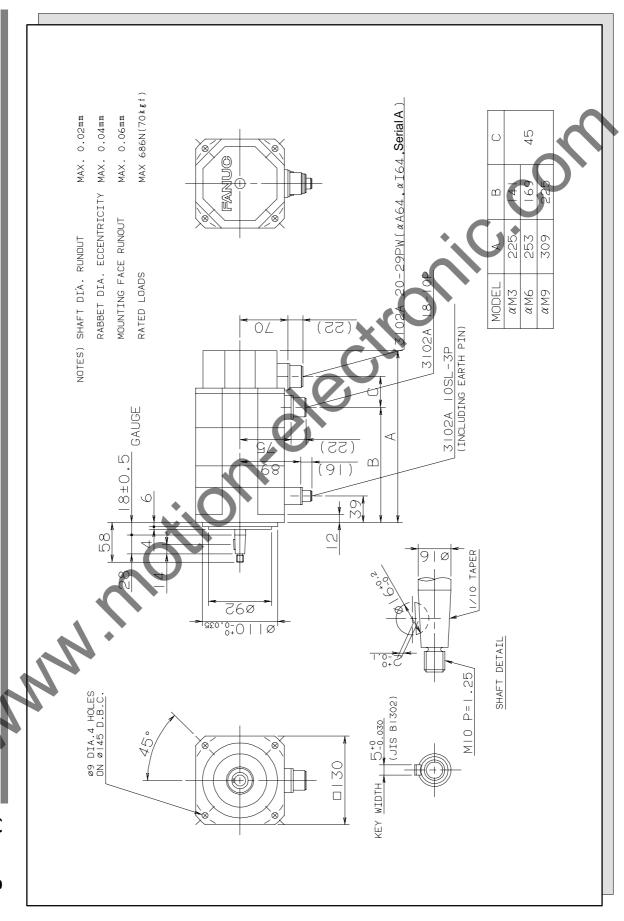


Fig. 3.3 (f) Models M6/3000 and M9/3000 (with the brake)



50.030 |8±0.5 GAUGE Fig. 3.3 (h) Model (M9/3000 (shaft option) 9 55 0+0 | | Ø A06B-0163-B(0) A06B-0163-B($\frac{5}{6}$) $\Box\Box$ OPTION(!) STRAIGHT SHAFT STANDARD TAPER SHAFT — 174 —

